# **Building Your Magnetic Field Mapper with LEGO®**

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# **UKMagSoc: Magnetic Measurement and Sensors**

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## Hall field mappers in 2007: Custom-built only

### Need:

- 3-Axis Hall sensor or array
- Positioning jig
- Temperature control
- Calibration

### • Get:

- 3 components of B
- Point-sampled
- Low to medium precision



From "Technologies for Precision Magnetic Field Mapping," presented at 2007 Magnetics Conference, Chicago, IL, USA



## Hall field mappers today: Choice of turn-key solutions









(www.senis.ch)



### World's first turn-key field mapper: Metrolab NMR Magnetic Field Camera







1992





# Metrolab's Hall Magnetometers: Single-point, but compact & 3-axis





Today

1995



## **3-Axis Hall Magnetometers** (a brief digression...)

- Advantages:
  - All vector components
  - Any probe orientation
- Challenges:
  - Orthogonality
  - Active volume size
  - Planar Hall Effect
  - Cost





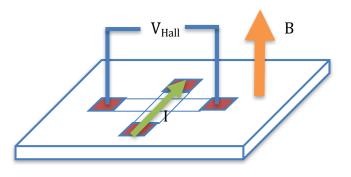
Credits:

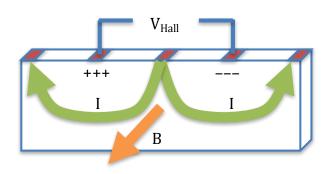
- LakeShore Cryotronics (Model 460)
- Magnetic Sciences Inc. (F.W. Bell 8030)



# **3-Axis Hall Magnetometers First revolution: integration**

- Vertical Hall sensor
  - Integrated 3-axis sensors
- Advantages:
  - Simplified construction
  - ~100 µm active volume
- Limitations:
  - Si: lower sensitivity, higher noise

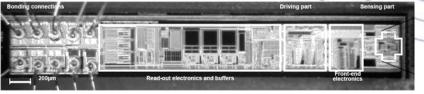




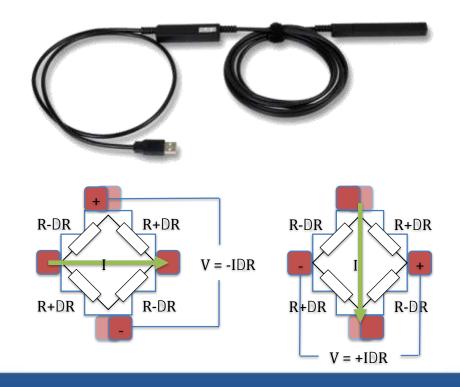


### **3-Axis Hall Magnetometers First revolution: more advantages**

- Integrated current source and amplifier
- Integrated temperature sensor
- "Spinning current" to minimize offset, Planar Hall Effect, and noise



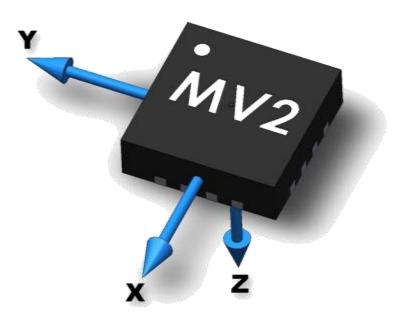
Credit: presentation by D. Popovic (Senis) at IMMW-14





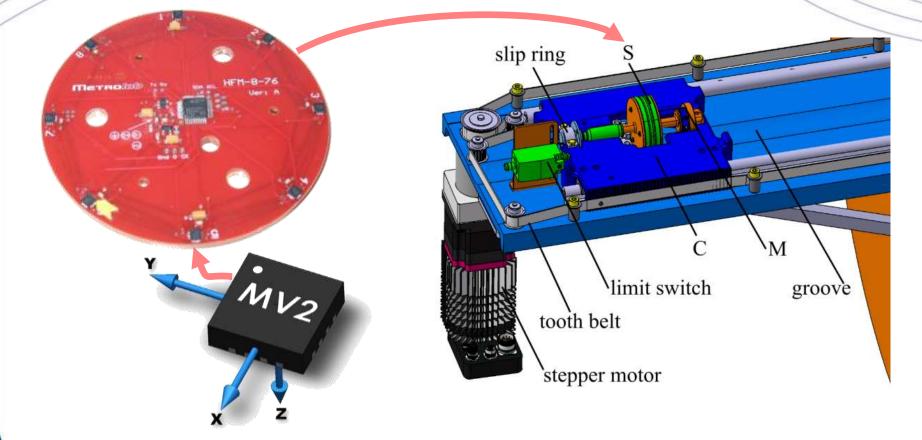
# **3-Axis Hall Magnetometers Second revolution: digitalization**

- Integrated ADC
  Digital interface
- Advantages:
  - Minimize system complexity & cost
  - Minimize errors from inductive voltages
  - Additional controls
  - Sensor arrays feasible
- Limitations:
  - ADC performance





## Metrolab's first Hall field mapper: Hall Magnetic Camera HMC9076



Sensor disc – Metrolab

#### Field mapper – FZ Jülich



## Hall Magnetic Camera HMC9076

### Advantages:

- 3-axis sensors
- Temp. stabilization (10<sup>-4</sup> accuracy)
- Parallelism for speed
- Simplicity: USB only
- Optimized positions
- Standardized design

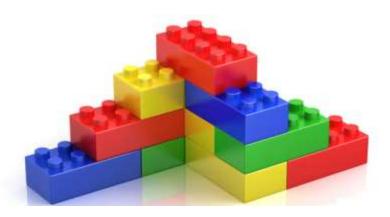
### Limitations:

- Customized layout
- Too large to calibrate in normal magnet (calibrated by customer at CERN)



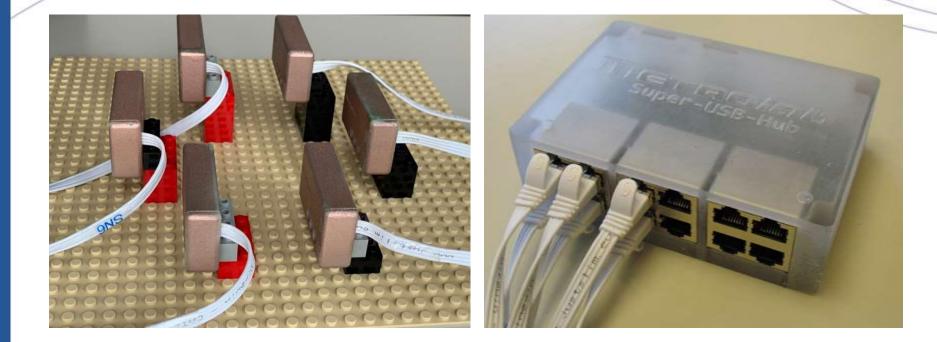
## **Concept: modular field mapper**

- Magnetic field measurement: network of small, independent, flexible, low-cost sensor modules
- Mechanical positioning: easily reconfigurable, expandable, little mechanical expertise





# First prototype: "MV2Lego"



#### Bricks

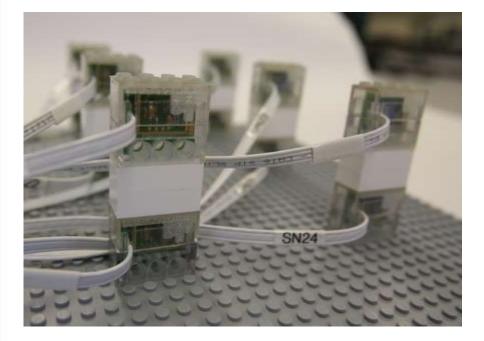
(USB power, control & communication, 5 holes for Technics axles)

### USB "Super-Hub"

(synchronization, non-magnetic connectors)



# **"MV2Lego" version 2**

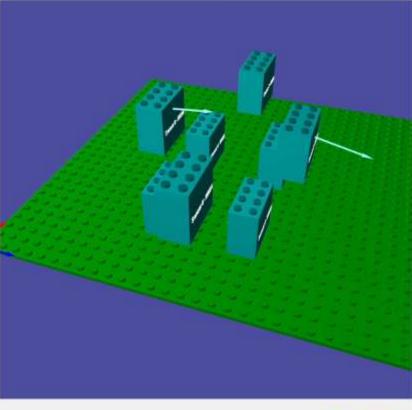


- Smaller: equivalent to stack of 3 2x4 bricks
- Standard 2x4 studs top/bottom
- 3 lateral holes for Technics axles
- Can remove LEGO housing
- Improved software



# **MV2Lego Software in Action**

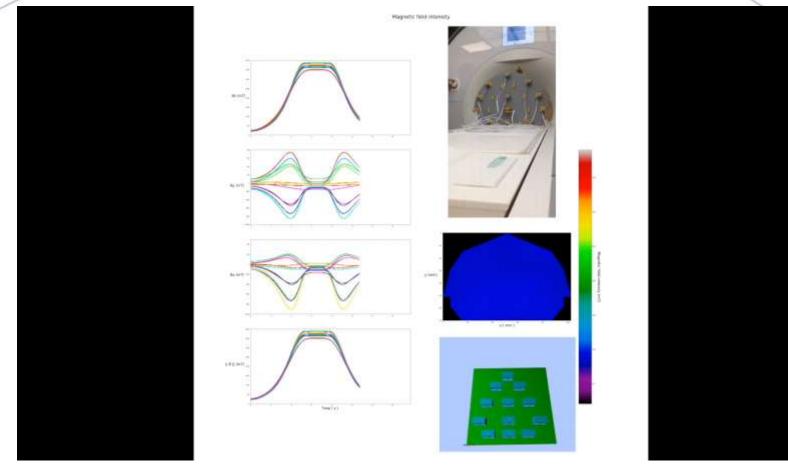
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Метнолав



## Early results: Longitudinal map of MRI magnet

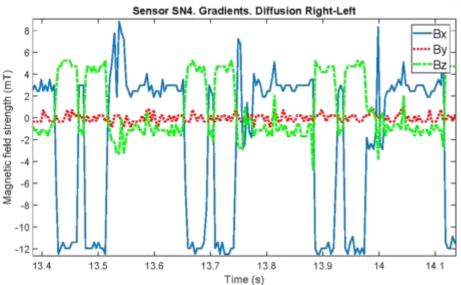


Joris Pascal (FHNW), Benjamin Roussel (Université de Lorraine), Julien Oster (INSERM-IADI)



### Early results: Measure MRI gradients

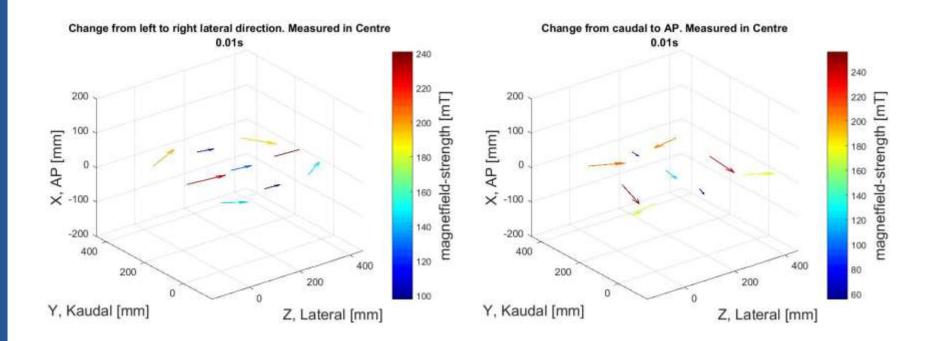




J. Pascal, N. Weber, J. Felblinger, J. Oster, "Magnetic gradient mapping of a 3T MRI scanner using a modular array of novel three-axis Hall sensors" (paper submitted to ISMRM 2018)

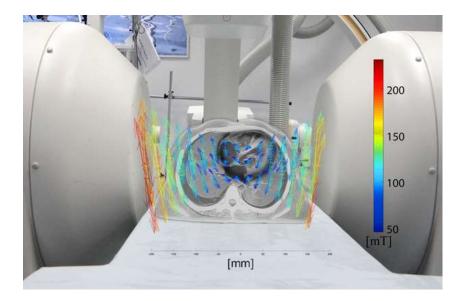


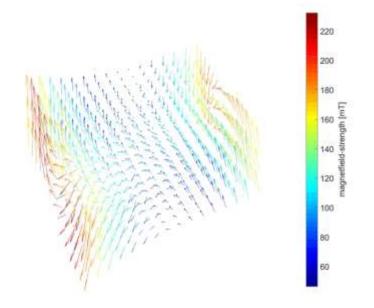
### Early results: Map remote magnetic navigation system





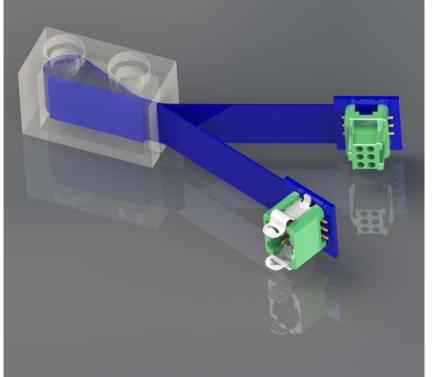
### Early results: Map remote magnetic navigation system







# Industrialization



- Smaller yet: higher point density
- Daisy-chained: less cabling
- Real LEGO bricks: quality, rights
- Part of THM line: Compatibility



**Key figures** 

### Magnetometer:

- Measurement ranges: 0.1, 0.3, 1, 3, 10, 30 T
- Resolution: 14, 15, 16, 16+ bits
- Sample rate: up to 3 kHz
- Active volume: 200x200x10 µm
- Triggered acquisition
- Calibrated

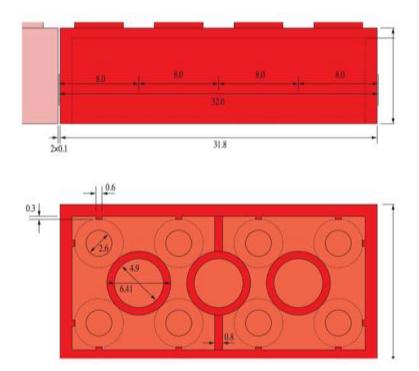
### Modularity:

- 1x2 LEGO brick
- Daisy-chains to ~5 m
- Synchronized trigger
- Contents:
  - Control unit
  - Bricks
  - Extension cables
  - Software
  - C++ interface library



# Why LEGO?

- Modularity
- Variety of elements (including Technic and Mindstorms)
- Availability
- Familiarity
- Cost
- Mechanical precision







### Mindstorms



A devotee and his project https://www.youtube.com/ watch?v=gsPTgKrJX8A



### My personal favorite: World-champion Rubik's Cube Solver





# Why not wireless?

- Complexity, size, cost: antenna, comm. chip, battery, charging system, firmware, more powerful µprocessor, …
- Ferromagnetic material in components
- RF interference (e.g. MRI scanners)





# Magnetic field mapping systems: reducing barriers to entry

- Low cost of entry
- Expandability
- Reconfigurability
- Large magnet systems
- Standard calibration
- Optimal sensor placement
- True 3-axis
- DC as well as AC fields

