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Three-axis magnetometer on a chip

Three-axis Hall magnetometers are traditionally top-of-the-line instruments – complex, bulky and expensive. A new magnetometer on a chip changes all that, opening new application areas

all effect devices are all around us today. Most are sensors such as magnetic switches, proximity sensors, and rotational sensors. In comparison, Hall magnetometers – whether for metrological or industrial monitoring applications – are a small niche. Nonetheless dozens of manufacturers offer such devices, with a wide range of size, performance and price. Three-axis Hall magnetometers, however, are rare, with fewer than 10 manufacturers. These instruments, which measure the complete magnetic field vector at a single point, offer the important advantage that the flux-density measurement is independent of the probe orientation.

Compact three-axis Hall magnetometers have existed for many years (Figure 1), but most are high-end bench-top instruments – and correspondingly expensive. In some applications their utility is limited by the separation between the B_x , B_y and B_z sensors, typically in the order of several millimeters. Finally, when measuring arbitrarily oriented fields, rather than fields mostly perpendicular to the Hall sensor, the planar Hall effect becomes an important source of error.¹

The first revolution

This picture has started to change in the past 15 years. The key development was the vertical Hall sensor, which, unlike the traditional planar Hall

Figure 1: The original handheld three-axis Hall magnetometer – the Metrolab THM7025 (1995)

Figure 2: Planar (left) and vertical Hall (right) sensors



sensor, measures a field component in the semiconductor plane (Figure 2). Combining a planar with two vertical Hall sensors on the same chip results in an integrated three-axis Hall sensor. Compared with a traditional three-axis probe consisting of three discrete sensors glued to a





cube, the integrated sensor simplifies construction and reduces the separation between the three sensors. Integrated sensors are typically only 100-200µm in diameter and 10µm thick, providing the closest thing available to vector measurement at a single point.

Of course there is a price to pay. To take advantage of modern IC manufacturing techniques, integrated sensors use a silicon substrate, which is not the best material for Hall sensors, and the sensitivity and noise figures suffer. In addition vertical Hall geometries are less favorable than planar ones.

But integrated sensors have other advantages. The same chip can also contain the input bias Figure 3: Compact three-axis Hall magnetometer using firstgeneration integrated three-axis sensor – the Metrolab THM1176 (2008)

Figure 4: The spinning current technique uses a set of switches to permute the inputs and outputs of the Hall element, effectively rotating the bias current by 90°. This does not change the measured Hall voltage, but changes the sign of the offset and planar Hall effect



current source and output amplifier, thus tremendously simplifying the overall complexity of the magnetometer (Figure 3). An integrated temperature sensor – providing the temperature of the Hall sensor itself, where it really counts – enables the flux-density measurements to be effectively compensated for temperature drift. Finally, an integrated sensor makes it feasible to implement the so-called 'spinning current' technique (Figure 4), which minimizes common sources of zero-field offset, minimizes the planar Hall effect, and acts as a chopper to minimize 1/f noise.²

The second revolution

The first revolution produced a three-axis magnetometer on a chip – except that it is still an analog device. A logical next step is to integrate an onboard analog-to-digital converter (ADC) and digital interface circuit (Figure 5). In addition to reducing the system complexity even further, this approach also minimizes error voltages due to Faraday induction in the signal cables. A digital interface also makes it feasible to add many more controls, for example to trade off measurement rate against noise.

This latest generation of integrated three-axis Hall sensors, marketed under the name of MagVector MV2, is housed in a 3 x 3mm QFN package and enables the user to select an analog or serial peripheral interface (SPI) output. Despite its small size, it is a capable magnetometer with selectable ranges from 0.1-30T, a noise density of 300nT/vHz, and an analog bandwidth of 50kHz. In digital mode, measurement rate can be traded against ADC resolution, ranging from 0.375-3kHz, and from 14-16bits, respectively.

Typical applications

This magnetometer-on-a-chip enables applications that were formerly not feasible, due to the size, cost and sensor separation of a three-axis Hall magnetometer. Metrolab itself uses it in its latest generation of NMR magnetometers.³ Another typical application is an industrial field-mapping system. Traditionally such systems consist of a single Hall probe mounted on a



mechanical scanning arm. Scanning the volume around a large magnet array can be extremely time-consuming. During the scan, the field map may change due to temperature drift. In addition, for cost reasons, a single-axis Hall magnetometer is often used, requiring complex, lengthy and error-prone computations to infer the missing field components.

In an industrial context, these constraints may not be acceptable. For example, magnetron sputtering systems use magnet arrays to help confine the plasma. Heat damage to these magnets can lead to uneven deposition, so it is increasingly common practice to map the magnets at regular intervals. Such a map can require hours of a technician's time, during which the sputtering system is probably shut down, entailing a large loss of production.

An effective way to minimize these costs is to use an array of sensors, acquiring data in parallel and dramatically reducing the mapping time Figure 5: Block diagram of the MagVector MV2, secondgeneration integrated three-axis Hall sensor

Figure 6: Multiple MagVector MV2 sensors wired in parallel

(Figure 6). In fact it may be possible to replace one of the scanning arm's degrees of freedom with a sensor array, thereby also reducing the cost of the mechanical system. With a single-chip magnetometer this all becomes feasible.

It may seem that with this level of integration, anyone who knows how to use a soldering iron could build an inexpensive, top-flight three-axis magnetometer. That is not quite true. Being an electronic peripheral component, the MagVector MV2 includes none of the amenities of a traditional magnetometer; the user must supply the microcontroller, control firmware, host interface and user interface. In addition, calibrating the gain, offset, temperature coefficients, non-linearity and nonorthogonality of a three-axis Hall magnetometer requires sophisticated equipment and procedures. The cost and effort of such a development project must be carefully weighed against the cost and convenience of an off-the-shelf instrument.

Conclusion

The MagVector MV2 represents a logical continuation of the evolution toward highly integrated three-axis Hall magnetometers. Its size, performance and cost open new possibilities for embedding a high-quality magnetometer in custom systems, such as those used for field mapping. It is, however, not a single-chip solution to every magnetic-field measurement problem; the vast majority of applications will continue to be better served by an off-the-shelf, professionally calibrated instrument. For technical reasons it may also prove to be unsuitable for certain applications, such as for extremely high precision, in very low fields or at cryogenic temperatures. ■

References

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